

SCHEME OF COURSE WORK

Course Details:

Course Title	Engineering Mechanics								
Course Code	15ME1101	L	T	P	C	3	1	0	4
Program:	B.Tech.								
Specialization:	Mechanical Engineering								
Semester	I								
Prerequisites	Trigonometry, Differential and Integral Calculus								
Courses to which it is a prerequisite	Mechanics of Solids, Kinematics of Mechanisms								

Course Outcomes (COs):

At the end of the course the student will be able to:

CO1	Convert a given physical problem (by drawing the Free body Diagrams) into a suitable force system and find i) the resultant force (if any) or, ii) the unknown reactions.
CO2	Solve problems involving static and kinetic friction.
CO3	Locate the centroid of a given plane area and find its area moment of inertia
CO4	Compute the mass moment of inertia of a body, Calculate the displacement, velocity and acceleration of a particle subjected to rectilinear or curvilinear translation.
CO5	Compute the motion of and torques on a body subjected to fixed axis rotation; Apply work-energy principles to particles and connected systems.

Program Outcomes (POs):

A graduate of Electrical & Electronics engineering will be able to

1	Apply the knowledge of basic sciences and electrical and electronics engineering fundamentals to solve the problems of power systems and drives.
2	Analyze power systems that efficiently generate, transmit and distribute electrical power in the context of present Information and Communications Technology.
3	Design and develop electrical machines and associated controls with due considerations to societal and environmental issues.
4	Design and conduct experiments, analyze and interpret experimental data for performance analysis.
5	Apply appropriate simulation tools for modeling and evaluation of electrical systems.
6	Apply the electrical engineering knowledge to assess the health and safety issues and their consequences.
7	Demonstrate electrical engineering principles for creating solutions for sustainable development.
8	Develop a techno ethical personality that help to serve the people in general and Electrical and Electronics Engineering in particular.
9	Develop leadership skills and work effectively in a team to achieve project objectives.
10	Communicate effectively in both verbal and written form.
11	Understand the principles of management and finance to manage project in multi disciplinary environments.
12	Pursue life-long learning as a means of enhancing the knowledge and skills.

Course Outcome Versus Program Outcomes:

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO-1	M		S									
CO-2			M									
CO-3			S									
CO-4	M		M									
CO-5	M		S									

S-Strongly correlated, M-Moderately correlated, Blank-No correlation

Assessment Methods:	Assignment/Seminar/ Mid-Test/End Exam
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Teaching-Learning and Evaluation

Week	TOPIC/CONTENTS	CO	Sample questions	TEACHING-LEARNING STRATEGY	Assessment Method & S schedule
1	Parallelogram law, forces and components, resultant of coplanar concurrent forces	CO1	Find the magnitude and direction of the four forces shown in Fig.	i. Lecture ii. Discussion iii. Problemsolving	
2	components of forces in space, moment of force, principle of moments, coplanar applications, couples, resultant if any force system (coplanar concurrent cases only)	CO1	Resolve the given force into 3 components along the directions shown. Find the moment of all the forces shown about the given moment-center	i. Lecture ii. Discussion iii. Problemsolving	
3	Equilibrium of force systems: Free body diagram, equations of equilibrium, equilibrium of planar systems,	CO1	Determine the support reactions of the body shown	i. Lecture ii. Discussion iii. Problemsolving	
4	Analysis of structures- method of joints, method of sections	CO1	Determine the internal force in all the members of the given truss	i. Lecture ii. Discussion iii. Problemsolving	
5	Theory of friction, angle of friction, laws of friction, static friction, kinetic friction	CO2	State the laws of friction. Differentiate between static and kinetic coefficient of friction	i. Lecture ii. Discussion iii. Problemsolving	
6	friction in bodies moving up or down on an inclined plane	CO2	Determine the forces in a rod connecting two bodies on a rough plane when motion is	i. Lecture ii. Discussion iii. Problemsolving	
7	wedge friction	CO2	Determine the forces developed in a wedge-block system	i. Lecture ii. Discussion iii. Problemsolving	Assignment 1
8	Center of gravity of flat plate, centroids of areas and lines, importance of centroid of areas and lines, importance of centroid and moment of area	CO3	Calculate the coordinates of the centroid of the given plane area	i. Lecture ii. Discussion iii. Problemsolving	
9	centroids determined by integration, centroid of composite figures, theorem of Pappus, center of gravity of bodies	CO3	Apply Pappus Theorem to calculate the surface area and volume of the solid of revolution shown	i. Lecture ii. Discussion iii. Problemsolving	Quiz 1
10	Definition of moment of inertia, polar moment of inertia, radius of gyration, parallel axis theorem, moments of inertia by integration, moments of inertia for composite areas	CO3	Determine the area moment of inertia of the plane area about the given x-, y-, and polar axes	i. Lecture ii. Discussion iii. Problemsolving	
11	MID-IE Examination				

12	Introduction, radius of gyration, parallel axis theorem, mass moments of inertia by integration, moments of inertia of composite bodies	CO4	Determine the mass moment of inertia of the given body about the given x-, y-, and polar axes	i. Lecture ii. Discussion iii. Problem solving	
13	Motion of a particle, rectilinear motion, rectangular components of curvilinear motion, normal and tangential components of acceleration	CO4	Determine the velocity and acceleration after 5 seconds for a particle moving on a curve shown	i. Lecture ii. Discussion iii. Problem solving	
14	Radial and transverse components, cylindrical coordinates, translation-analysis as a particle, further discussion of particle kinematics	CO4	Determine the velocity and acceleration of a rocket for the given data	i. Lecture ii. Discussion iii. Problem solving	Assignment 2
15	Types of rigid-body motion, angular motion-fixed axis rotation, application of kinematic equations, kinetic of fixed axis rotation.	CO5	Determine the angular velocity and displacement of a motor of given dimensions and density subjected to a given torque	i. Lecture ii. Discussion iii. Problem solving	
16	Work-energy equation for translation, interpretation and computation of work, work-energy applied to particle motion, power, efficiency	CO5	Find the velocity of the falling weight hanging from a string wound around a pulley as shown	i. Lecture ii. Discussion iii. Problem solving	Quiz
17	Work Energy applied to fixed-axis rotation, work-energy applied to connected	CO5	For the connected system of bodies, determine the forces in all strings 5 seconds after motion starts	i. Lecture ii. Discussion iii. Problem solving	
18	MID-II Examination				